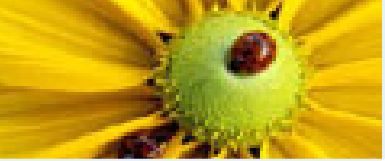


Crouzeix's Conjecture

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Courant Institute of Mathematical Sciences
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Joint work with
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Hong Kong, October 2022



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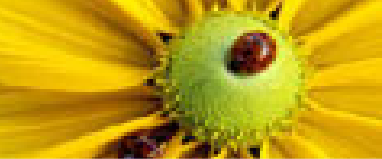
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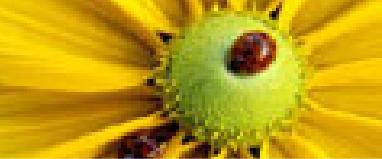
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For $A \in \mathbb{C}^{n \times n}$, the field of values (or numerical range) of A is

$$W(A) = \{v^* A v : v \in \mathbb{C}^n, \|v\|_2 = 1\} \subset \mathbb{C}.$$



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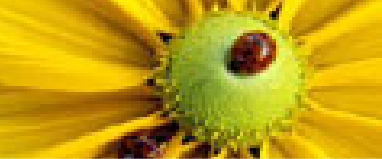
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$$W(A) \supseteq \sigma(A)$$

where σ denotes spectrum.



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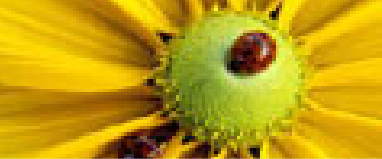
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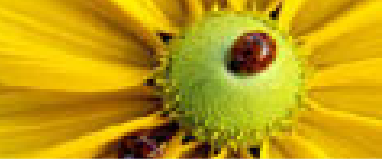
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Toeplitz-Hausdorff Theorem: $W(A)$ is convex for all $A \in \mathbb{C}^{n \times n}$.



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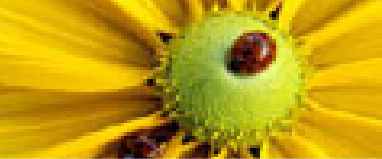
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Let

$$J = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} : \quad W(J) \text{ is a disk of radius } 0.5$$



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$$D = \begin{bmatrix} 5 + i & 0 \\ 0 & 5 - i \end{bmatrix} : \quad W(D) \text{ is a line segment}$$

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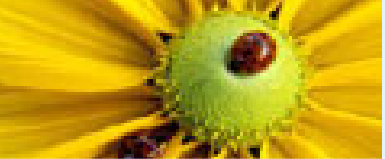
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$$D = \begin{bmatrix} 5+i & 0 \\ 0 & 5-i \end{bmatrix} : \quad W(D) \text{ is a line segment}$$

$$A = \text{diag}(J, B, D) : \quad W(A) = \text{conv}(W(J), W(B), W(D))$$



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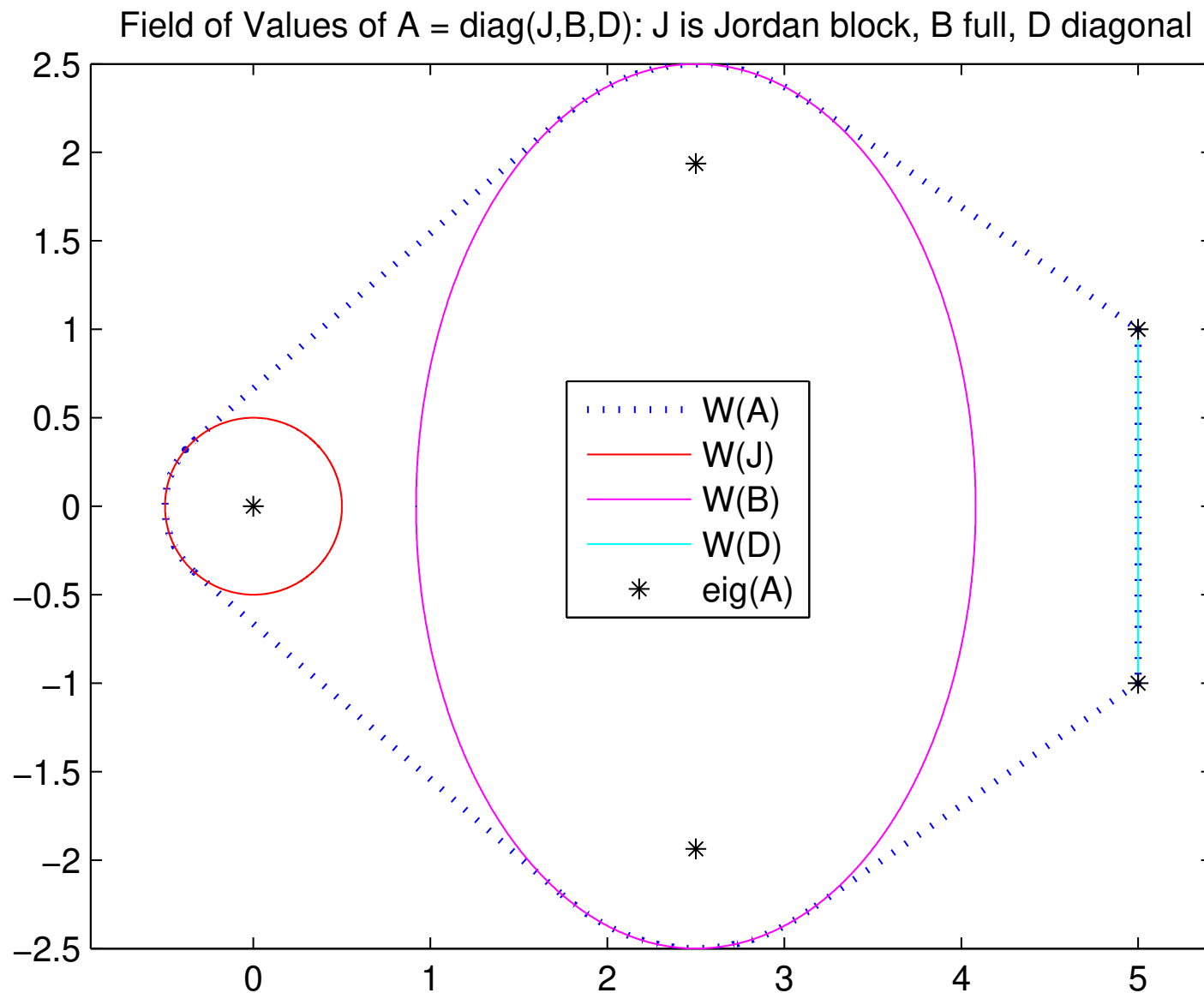
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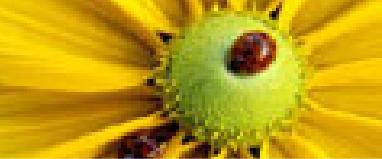
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Complex plane plot of field of values of $A = \text{diag}(J, B, D)$



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Let $p = p(z)$ be a polynomial and let A be a square matrix.

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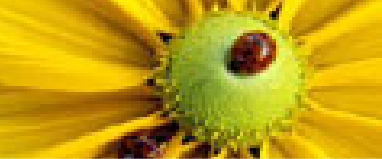
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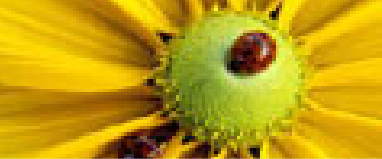
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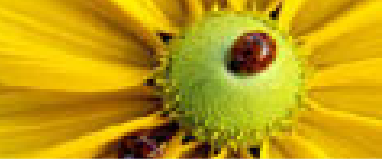
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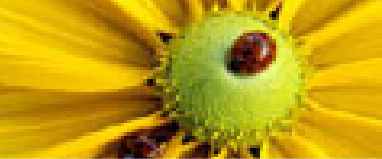
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If $p = \chi(A)$, the characteristic polynomial (or minimal polynomial) of A , then $\|p(A)\|_2 = 0$ by Cayley-Hamilton, but $\|p\|_{W(A)} = 0$ only if $A = \lambda I$ for $\lambda \in \mathbb{C}$, so that $W(A) = \{\lambda\}$.

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If $p(z) = z$ and A is a 2×2 Jordan block with 0 on the diagonal, then $\|p(A)\|_2 = 1$ and $W(A)$ is a disk centered at 0 with radius 0.5, so the left and right-hand sides are equal.

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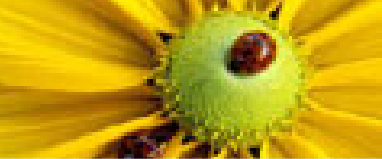
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Conjecture extends to analytic functions and to Hilbert space

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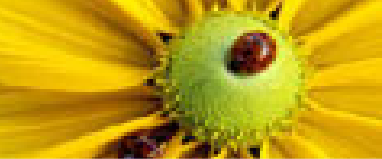
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GMRES is the Generalized Minimum Residual method for solving $Ax = b$, where $A \in \mathbb{R}^{n \times n}$ (Saad and Schultz, 1986).

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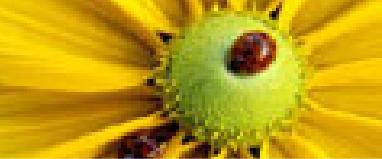
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Eigenvalues of A say nothing: *any* nonincreasing sequence of residual norms $\|r_m\| = \|Ax_m - b\|$ can be obtained for some A having *any* given eigenvalues (Greenbaum, Ptak, Strakoš, 1996).

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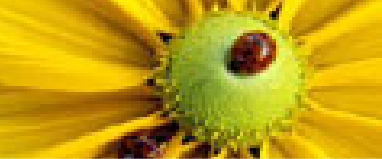
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However by definition of GMRES,

$$\|r_m\| = \min_{p \in P^m: p(0)=1} \|p(A)r_0\|$$

where P^m is the space of polynomials of degree m or less.

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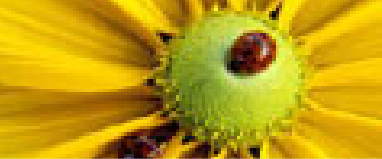
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However by definition of GMRES,

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where P^m is the space of polynomials of degree m or less.

So, if Crouzeix's conjecture is true, then

$$\frac{\|r_m\|}{\|r_0\|} \leq 2 \min_{p \in P^m: p(0)=1} \|p\|_{W(A)}.$$

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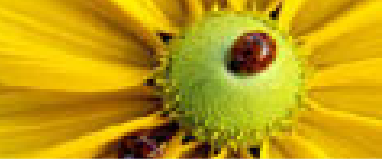
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A Specific Application: Convergence of GMRES

GMRES is the Generalized Minimum Residual method for solving $Ax = b$, where $A \in \mathbb{R}^{n \times n}$ (Saad and Schultz, 1986).

Eigenvalues of A say nothing: *any* nonincreasing sequence of residual norms $\|r_m\| = \|Ax_m - b\|$ can be obtained for some A having *any* given eigenvalues (Greenbaum, Ptak, Strakoš, 1996).

However by definition of GMRES,

$$\|r_m\| = \min_{p \in P^m: p(0)=1} \|p(A)r_0\|$$

where P^m is the space of polynomials of degree m or less.

So, if Crouzeix's conjecture is true, then

$$\frac{\|r_m\|}{\|r_0\|} \leq 2 \min_{p \in P^m: p(0)=1} \|p\|_{W(A)}.$$

If $0 \in W(A)$, then this is useless, but one can instead consider $B = A^{1/q}$ where q is chosen large enough that $0 \notin W(B)$.

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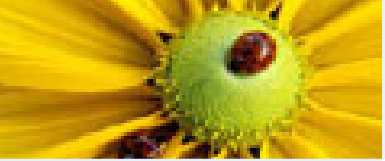
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Crouzeix's Theorem

$$\|p(A)\|_2 \leq 11.08 \|p\|_{W(A)}$$

i.e., the conjecture is true if we replace 2 by 11.08.

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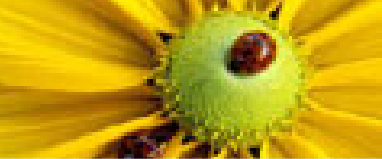
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$$\|p(A)\|_2 \leq 11.08 \|p\|_{W(A)}$$

i.e., the conjecture is true if we replace 2 by 11.08.

“The estimate 11.08 is not optimal. There is no doubt that refinements are possible which would decrease this bound. We are convinced that our estimate is very pessimistic, but to improve it drastically (recall that our conjecture is that 11.08 can be replaced by 2), it is clear that we have to find a completely different method.”

- Michel Crouzeix, “Numerical range and functional calculus in Hilbert space”, *J. Funct. Anal.* 244 (2007).



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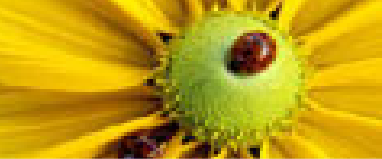
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- Michel Crouzeix, “Numerical range and functional calculus in Hilbert space”, *J. Funct. Anal.* 244 (2007).

Remarkably broad impact: the norm of an analytic function of a matrix A is bounded by a modest constant times its norm on the field of values $W(A)$.



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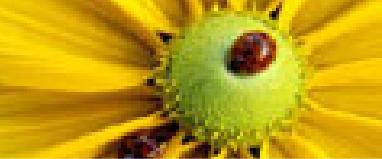
$$\|p(A)\|_2 \leq (1 + \sqrt{2}) \|p\|_{W(A)}$$

i.e., the conjecture is true if we replace 2 by $1 + \sqrt{2}$

Presented at a conference in Greece, 2016

Published in a SIMAX paper with Crouzeix, 2017

Much cleaner proof than that of Crouzeix's previous bound. Uses novel but relatively brief arguments based on complex analysis.



Special Cases

The conjecture is known to hold for certain restricted classes of polynomials $p \in P^m$ or matrices $A \in \mathbb{C}^{n \times n}$.

Let $r(A) = \max_{\zeta \in W(A)} |\zeta|$ (numerical radius) and $\mathcal{D} =$ open unit disk

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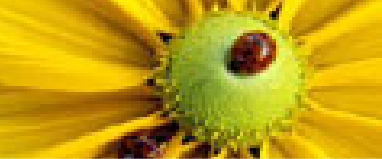
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- $p(\zeta) = \zeta^m$:
 $\|A^m\| \leq 2r(A^m) \leq 2r(A)^m = 2 \max_{\zeta \in W(A)} |\zeta^m|$
(power inequality, Berger 1965, Percy 1966)

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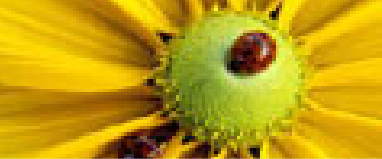
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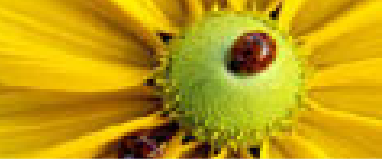
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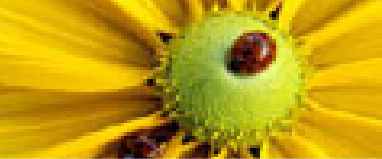
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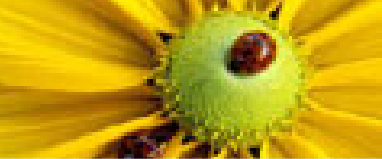
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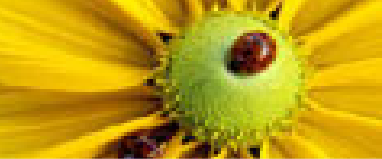
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- $AA^* = A^*A$ (then the constant 2 can be improved to 1).

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The extreme points of a convex set are those that cannot be expressed as a convex combination of two other points in the set.

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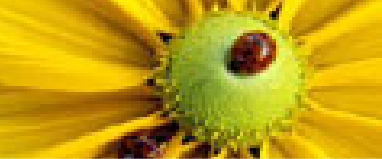
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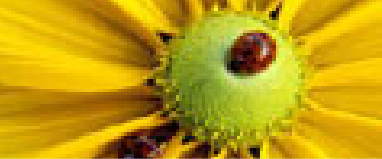
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Based on R. Kippenhahn (1951), C.R. Johnson (1978) observed that the extreme points of $W(A)$ can be characterized as

$$\text{ext } W(A) = \{z_\theta = v_\theta^* A v_\theta : \theta \in [0, 2\pi)\}$$

where v_θ is a normalized eigenvector corresponding to the largest eigenvalue of the Hermitian matrix

$$H_\theta = \frac{1}{2} \left(e^{i\theta} A + e^{-i\theta} A^* \right).$$



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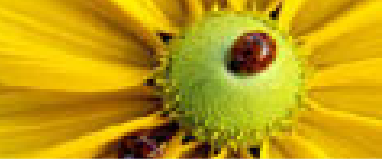
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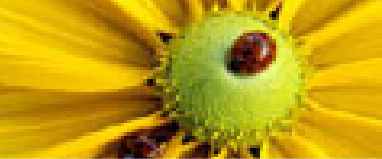
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Thus, we can compute as many extreme points as we like.
Continuing with the previous example...



Johnson's Algorithm Finds the Extreme Points

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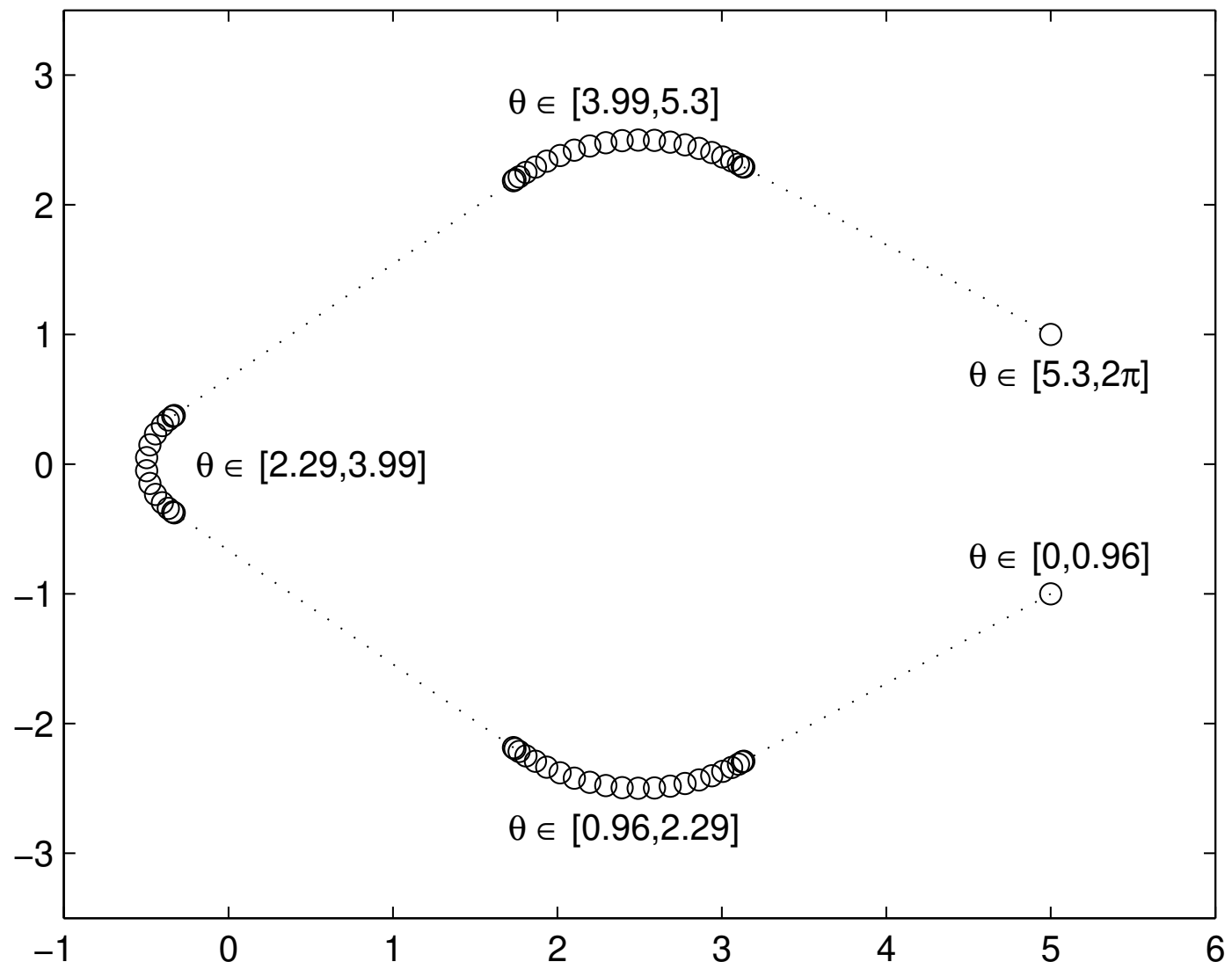
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The extreme points of $W(A)$ lie in the union of 5 connected sets



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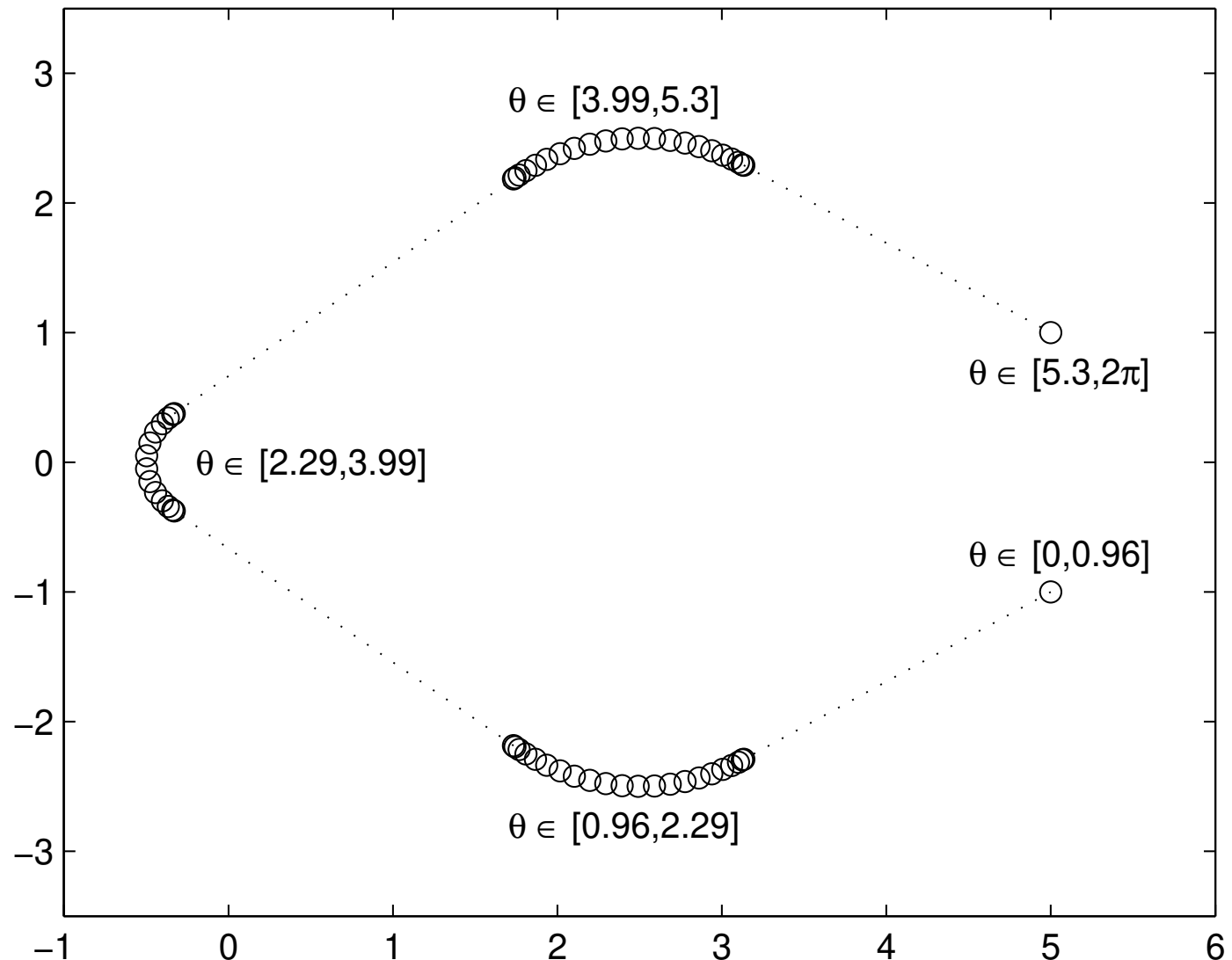
Computing the
Crouzeix Ratio

Nonsmooth

Optimization of
the Crouzeix Ratio f

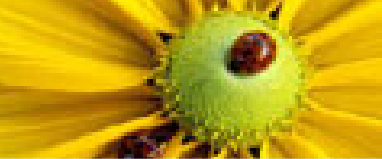
Nonsmooth Analysis
of the Crouzeix Ratio

Concluding Remarks



The extreme points of $W(A)$ lie in the union of 5 connected sets

But how can we do this accurately, automatically and efficiently?



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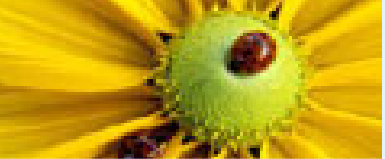
Concluding Remarks

Chebfun (Trefethen et al, 2004–present) represents real- or complex-valued functions on real intervals to machine precision accuracy using Chebyshev interpolation.

The necessary degree of the polynomial is determined automatically. For example, representing $\sin(\pi x)$ on $[-1, 1]$ to machine precision requires degree 19.

Most MATLAB functions are overloaded to work with chebfun's.

Applying Chebfun's **fov** to compute the boundary of $W(A)$ for the previous example...



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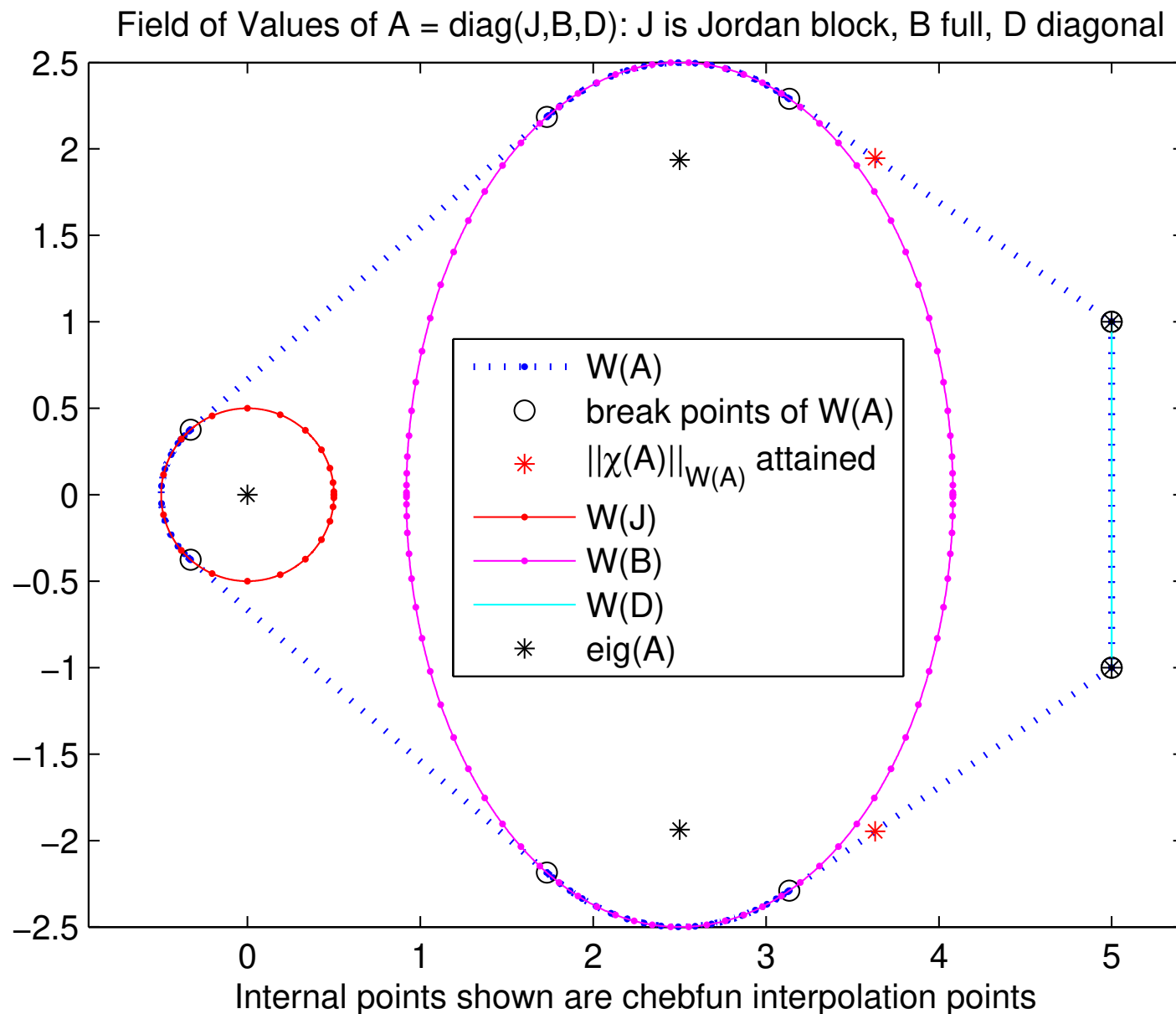
[Optimization of](#)

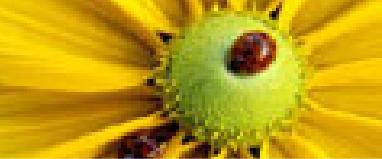
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The Crouzeix Ratio

Define the Crouzeix ratio

$$f(p, A) = \frac{\|p\|_{W(A)}}{\|p(A)\|_2}.$$

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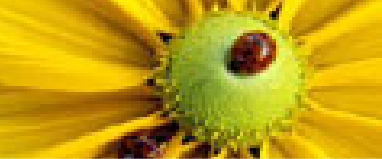
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$$f(p, A) = \frac{\|p\|_{W(A)}}{\|p(A)\|_2}.$$

The conjecture states that $f(p, A)$ is bounded below by 0.5 independently of the polynomial degree m and the matrix order n .

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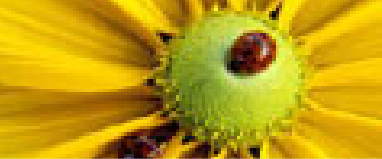
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The Crouzeix ratio f is

- A mapping from $\mathbb{C}^{m+1} \times \mathbb{C}^{n \times n}$ to \mathbb{R} (associating polynomials $p \in P^m$ with their vectors of coefficients $c \in \mathbb{C}^{m+1}$ using the monomial basis)

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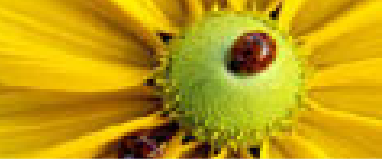
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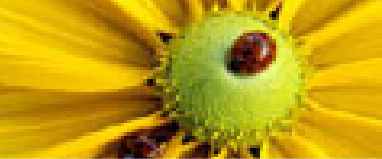
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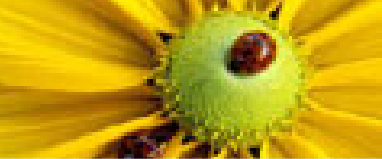
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- Not convex
- Not defined if $p(A) = 0$
- Lipschitz continuous at all other points, but not necessarily differentiable
- Semialgebraic (its graph is a finite union of sets, each of which is defined by a finite system of polynomial inequalities)

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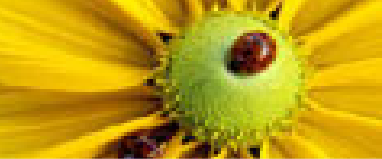
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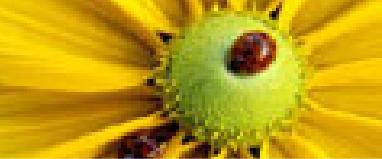
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Numerator: use Chebfun's **fov** (modified to return any line segments in the boundary) combined with its overloaded **polyval** and **norm(·,inf)**.



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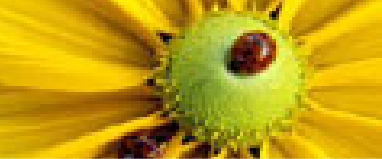
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Denominator: use MATLAB's standard **polyvalm** and **norm(·,2)**.



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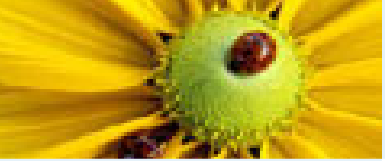
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The main cost is the construction of the chebfun defining the field of values.



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Is the Ratio 0.5
Attained?

How Could we
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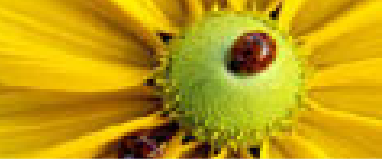
Why is the Crouzeix
Ratio One?

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Degree $n - 1$

An Apparent Local
Minimum: $N = 14$

What if we Fix p and
Optimize over A ?

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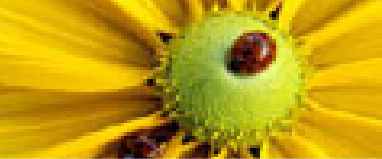
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- When the max value of $|p(z)|$ on $\text{bd } W(A)$ is attained at more than one point z (the most important, as this frequently occurs at apparent minimizers)



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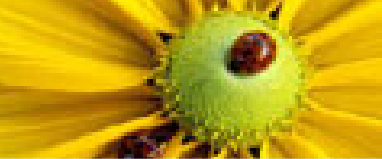
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- Even if such z is unique, when the normalized vector v for which $v^*Av = z$ is not unique up to a scalar, implying that the maximum eigenvalue of the corresponding H_θ matrix has multiplicity two or more (does not seem to occur at minimizers)



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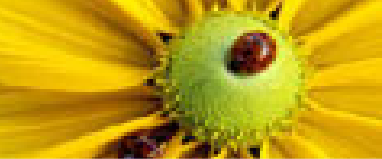
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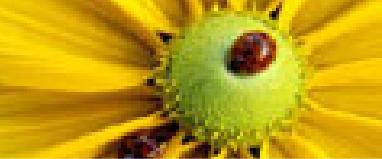
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- When the maximum singular value of $p(A)$ has multiplicity two or more (does not seem to occur at minimizers)

In all of these cases the gradient of f is not defined.

But in practice, none of these cases ever occur, except the first one *in the limit*.



BFGS

BFGS (Broyden, Fletcher, Goldfarb and Shanno, all independently in 1970), is the standard quasi-Newton algorithm for minimizing smooth (continuously differentiable) functions.

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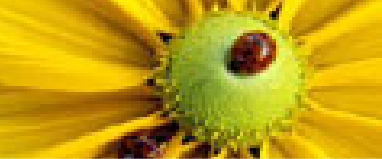
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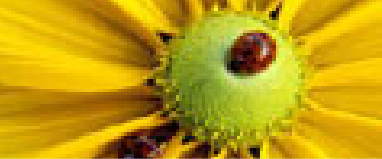
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It works by building an approximation to the Hessian of the function using gradient differences, and has a well known superlinear convergence property under a regularity condition.



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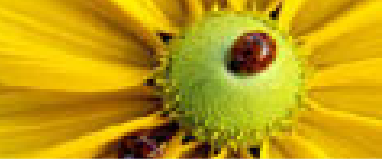
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It works by building an approximation to the Hessian of the function using gradient differences, and has a well known superlinear convergence property under a regularity condition.

Although its global convergence theory is limited to the convex case (Powell, 1976), it generally finds local minimizers efficiently in the nonconvex case too, although there are pathological counterexamples.



BFGS

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Nonsmoothness of
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Experiments

Optimizing over A
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Final Fields of Values
for Lowest Computed
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Optimizing over both
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Is the Ratio 0.5
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How Could we
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Final Fields of Values
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Why is the Crouzeix
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Results for Larger
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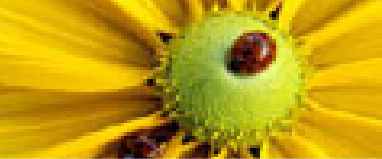
An Apparent Local
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Although its global convergence theory is limited to the convex case (Powell, 1976), it generally finds local minimizers efficiently in the nonconvex case too, although there are pathological counterexamples.

Remarkably, this property seems to extend to nonsmooth functions too, with a linear rate of local convergence, although the convergence theory is extremely limited (Lewis and Overton, 2013). It builds a very ill conditioned “Hessian” approximation, with “infinitely large” curvature in some directions and finite curvature in other directions.



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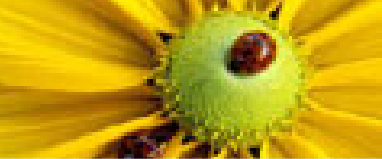
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For fixed n , optimize over A with order n and p of $\deg \leq n - 1$, running BFGS for a maximum of 1000 iterations from each of 100 randomly generated starting points.



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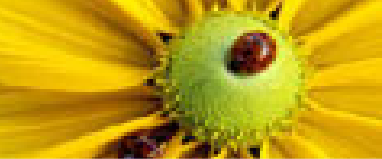
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We restrict p to have real coefficients and A to be real, in Hessenberg form (all but one superdiagonal is zero).



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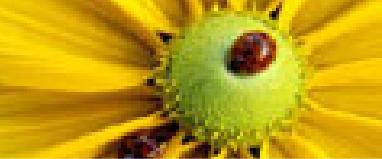
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We have obtained similar results for p with complex coefficients and complex A (then can take A to be triangular).



Optimizing over A (order n) and p ($\deg \leq n - 1$)

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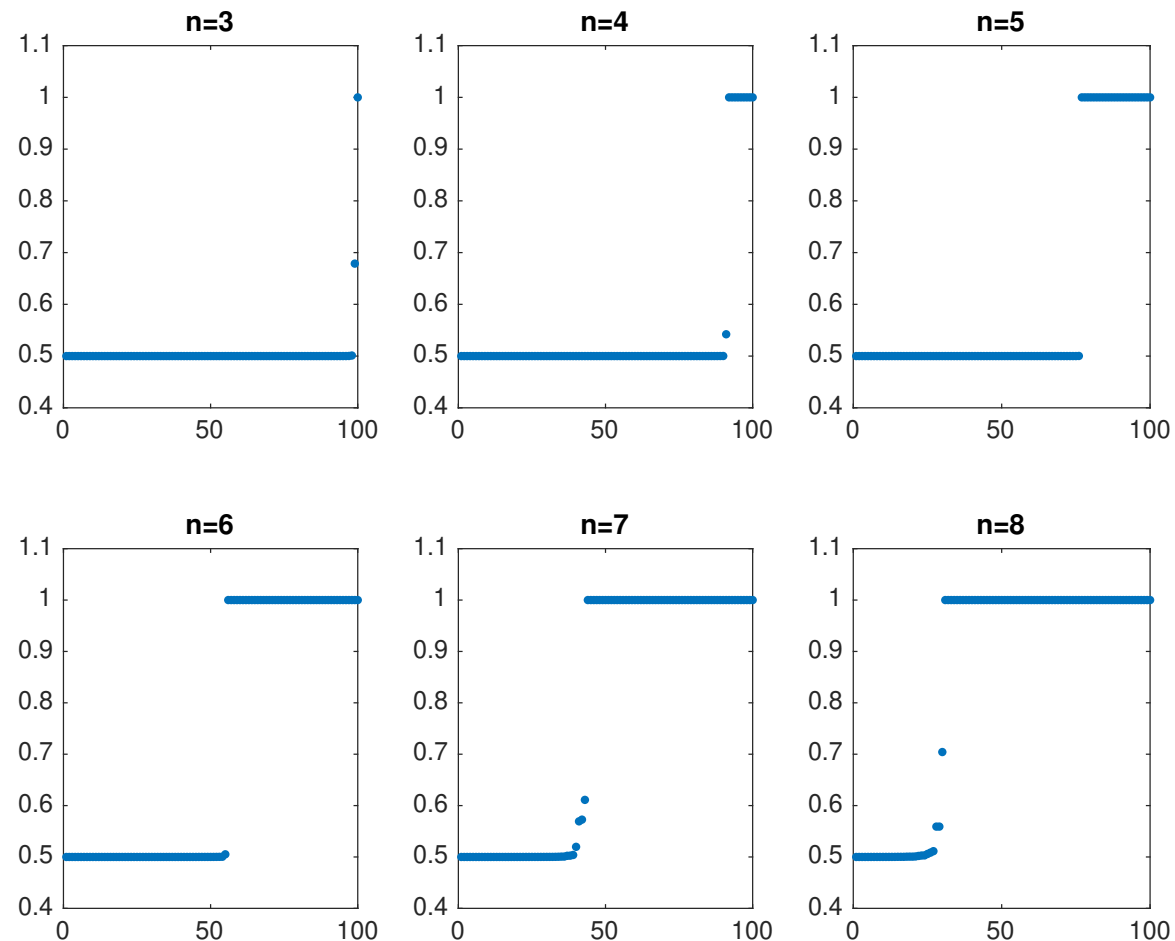
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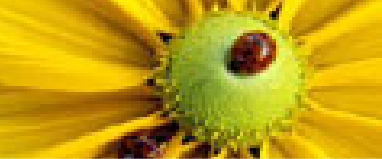
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Sorted final values of the Crouzeix ratio f
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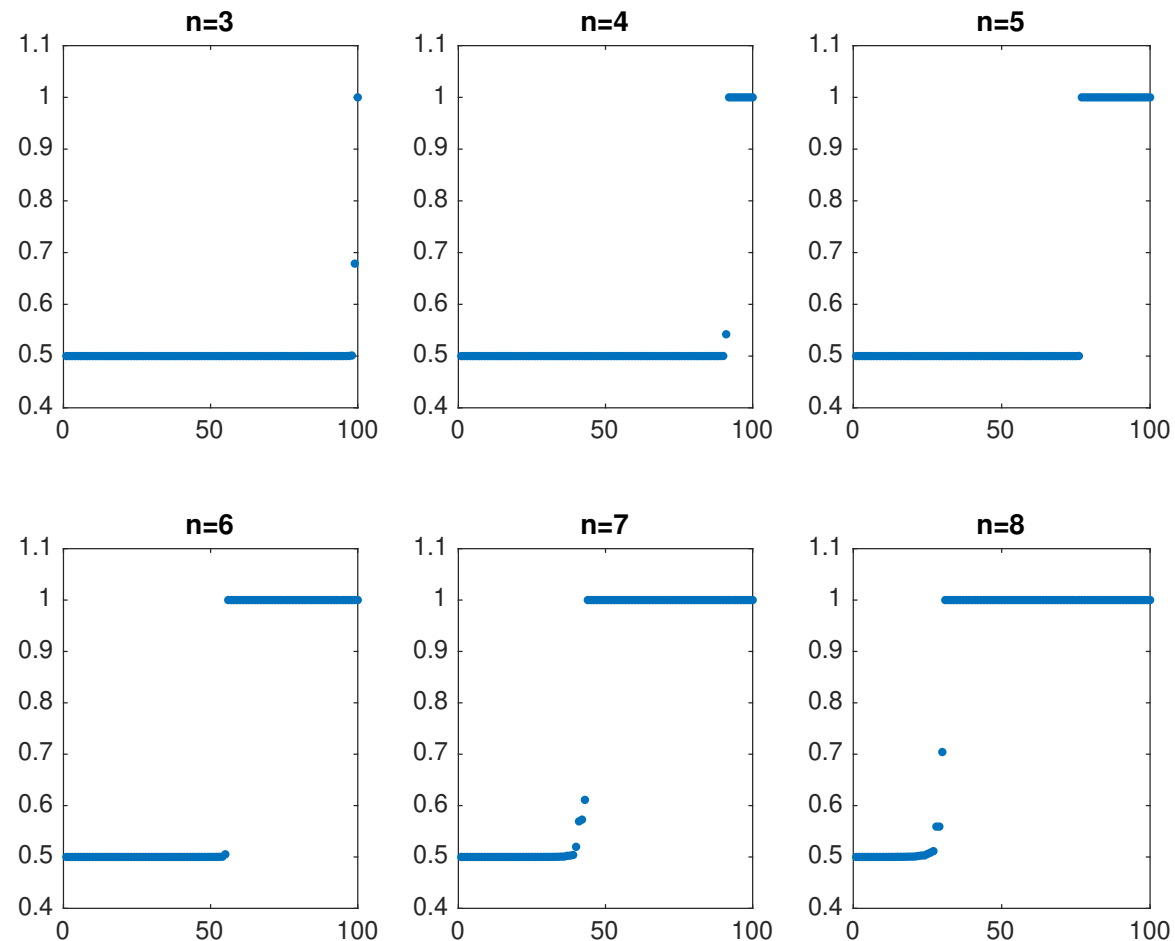
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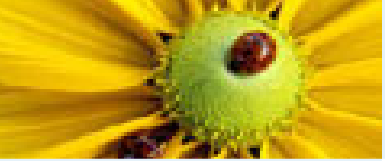
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Are 0.5 and 1 the only locally optimal values of f ?



Final Fields of Values for Lowest Computed f

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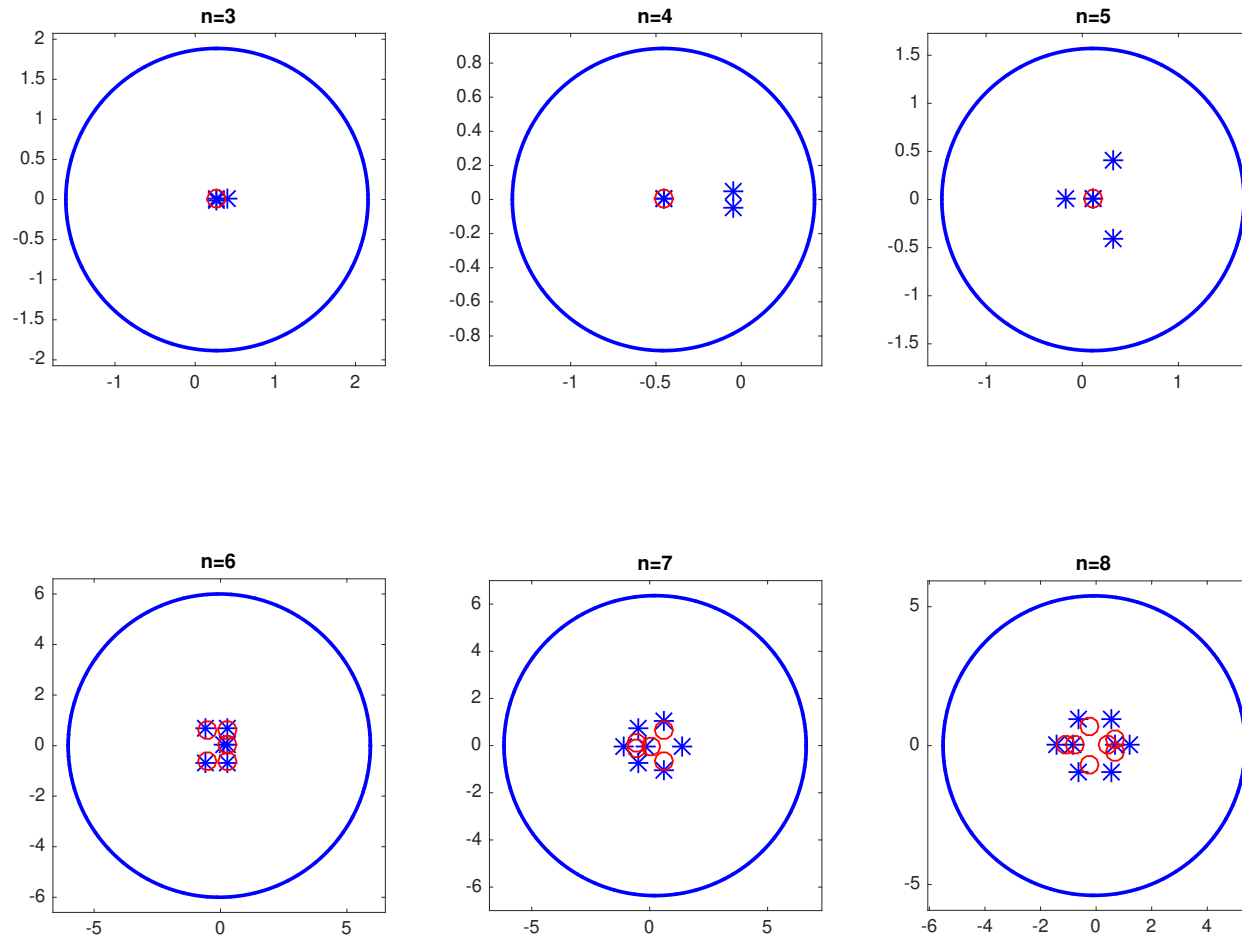
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What if we Fix p and
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Solid blue curve is boundary of field of values of final computed A
Blue asterisks are eigenvalues of final computed A
Small red circles are roots of final computed p



Final Fields of Values for Lowest Computed f

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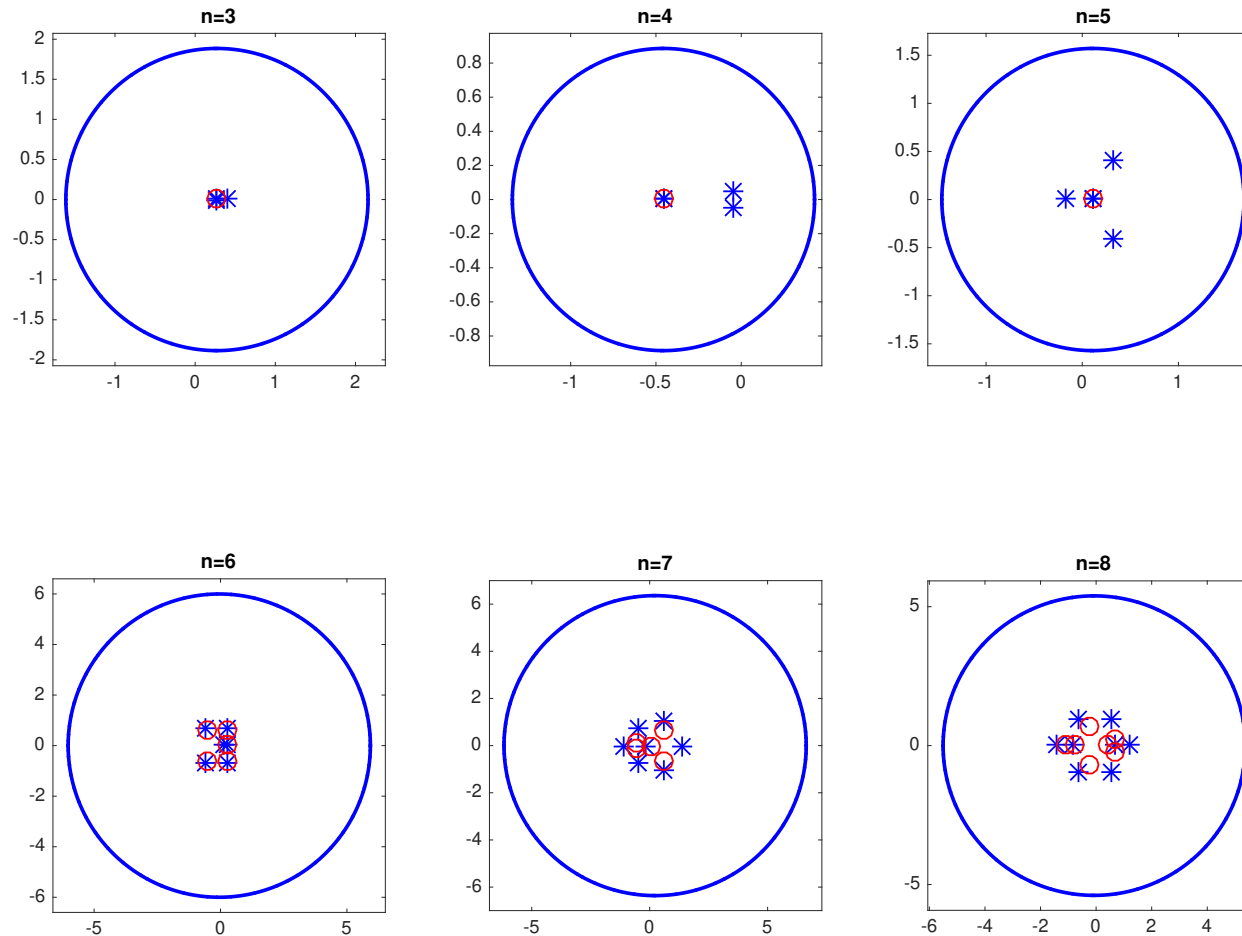
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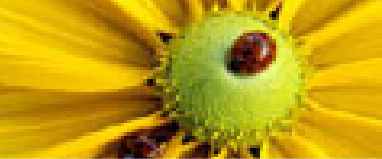


Solid blue curve is boundary of field of values of final computed A

Blue asterisks are eigenvalues of final computed A

Small red circles are roots of final computed p

$n = 3, 4, 5$: two eigenvalues of A and one root of p nearly coincident



Optimizing over both p and A : Final $f(p, A)$

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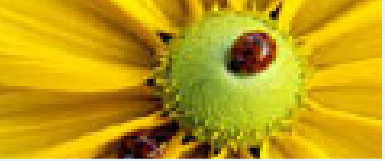
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n	f
3	0.5000000000000000
4	0.5000000000000000
5	0.5000000000000014
6	0.500000017156953
7	0.500000746246673
8	0.500000206563813

f is the lowest value $f(p, A)$ found over 100 runs



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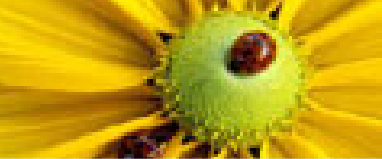
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for which $W(A)$ is the closed unit disk $\overline{\mathcal{D}}$.

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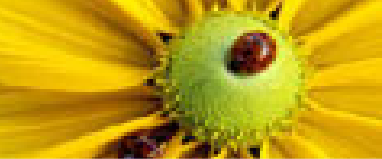
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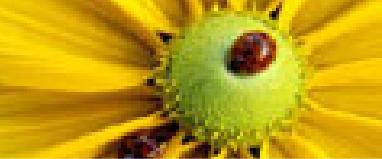
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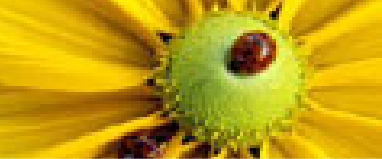
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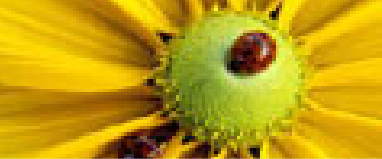
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However, this is not true if we allow p to be any analytic function. (Crouzeix has a complete analysis for $n = 3$.)

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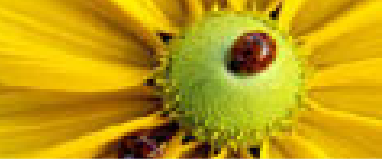
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Note: f is *nonsmooth* at these pairs (p, A) because $|p|$ is constant on the boundary of $W(A)$.

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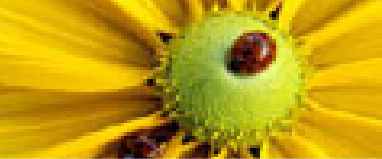
Final Fields of Values
for f Closest to 1

Why is the Crouzeix
Ratio One?

Results for Larger
Dimension n and
Degree $n - 1$

An Apparent Local
Minimum: $N = 14$

What if we Fix p and
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How Could we Recognize such Minimizers?

Crouzeix's Conjecture

Nonsmooth
Optimization of
the Crouzeix Ratio f

Nonsmoothness of
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BFGS

Experiments

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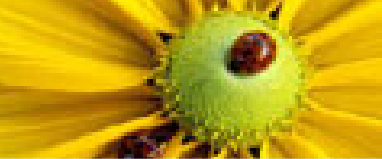
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Using the GNSD (Generalized Null Space Decomposition), aka Staircase Form (Kublanovskaya 1966, Ruhe 1970, Golub-Wilkinson 1976, Van Dooren 1979, Kågström-Ruhe 1980, Edelman-Ma 2000, Guglielmi-Overton-Stewart 2015)...



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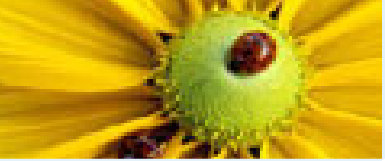
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We find that computed minimizers have the form

$$A = \lambda I + \alpha U \text{diag}(\Xi_k, B) U^T + E,$$

$$p(\zeta) = c_{n-1}(\zeta - \lambda)^{n-1} + \dots + c_1(\zeta - \lambda) + c_0$$

where $k \geq 2$ (usually $k = 2$), $\alpha \neq 0$, U is orthogonal, $W(B) \subset \overline{\mathcal{D}}$, $\|E\|$ is small and $|c_j|$ is small for $j \geq k$.



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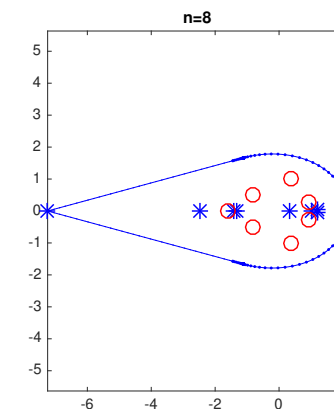
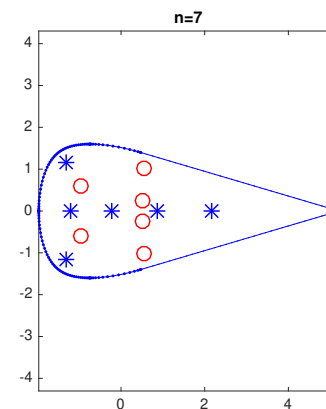
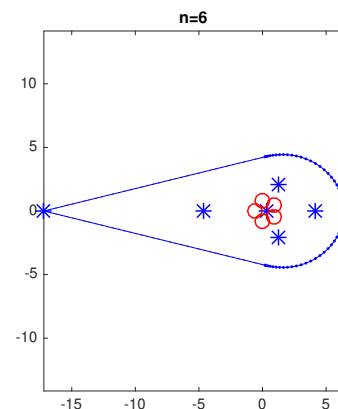
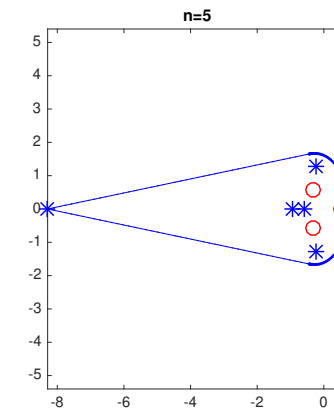
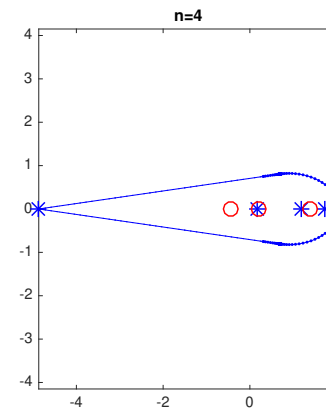
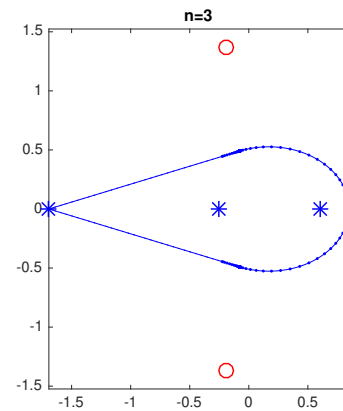
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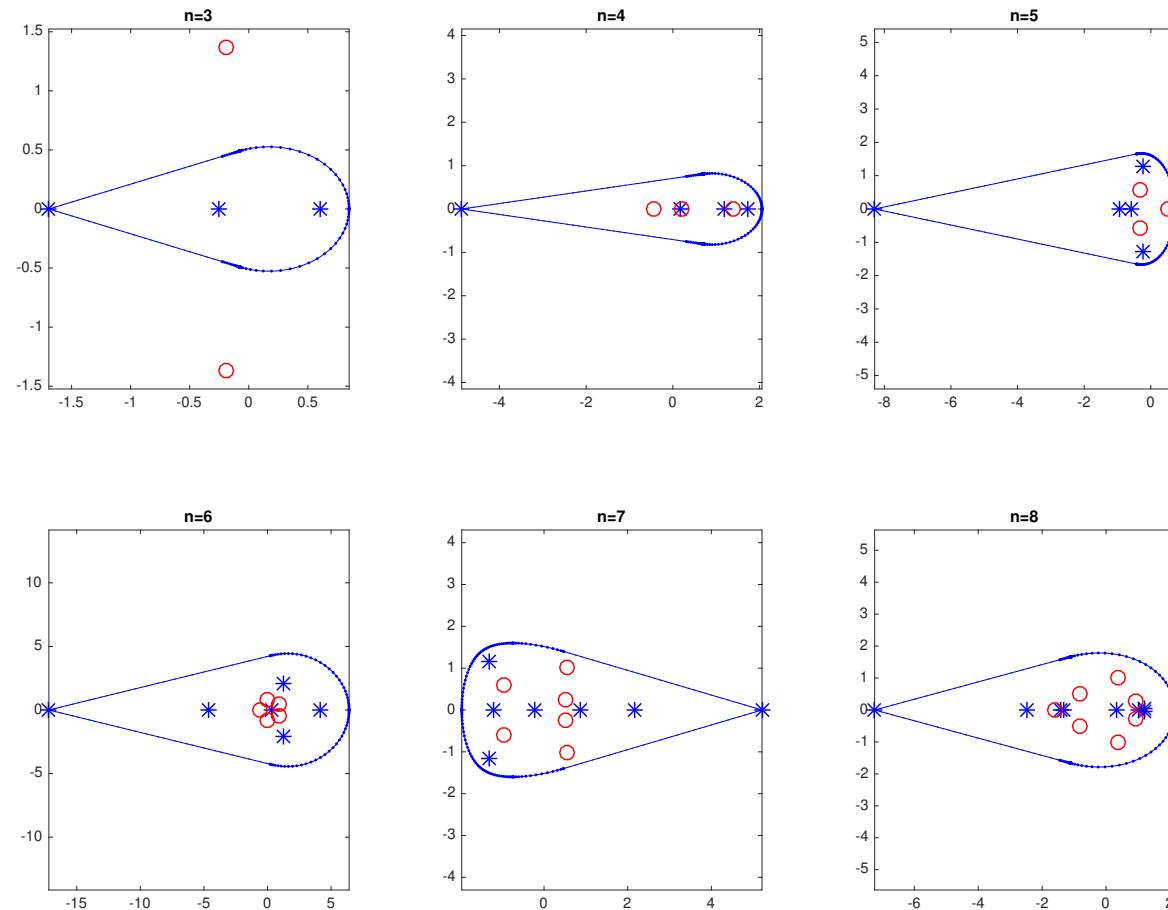
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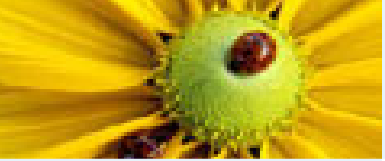
Ice cream cone shape:

exactly one eigenvalue at a vertex of the field of values

Solid blue curve is boundary of field of values of final computed A

Blue asterisks are eigenvalues of final computed A

Small red circles are roots of final computed p



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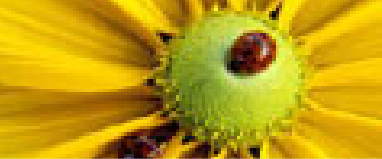
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Why is the Crouzeix Ratio One?

Because for this computed local minimizer, A is nearly unitarily similar to a block diagonal matrix

$$\text{diag}(\lambda, B), \quad \lambda \in \mathbb{R}$$

so

$$W(A) \approx \text{conv}(\lambda, W(B))$$

with λ *active* and the block B *inactive*, that is:

- $\|p\|_{W(A)}$ is attained only at λ
- $|p(\lambda)| > \|p(B)\|_2$

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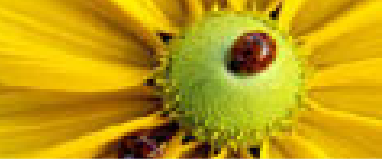
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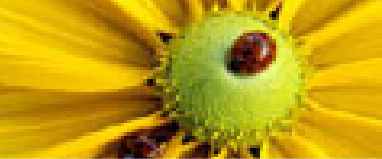
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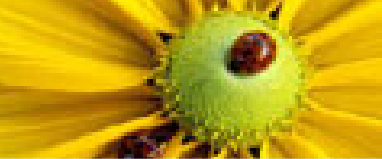
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As n increases, ice cream cone stationary points become increasingly common and it becomes very difficult to reduce f below 1.

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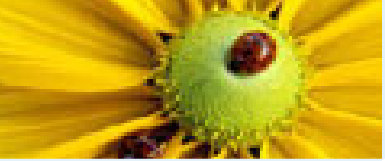
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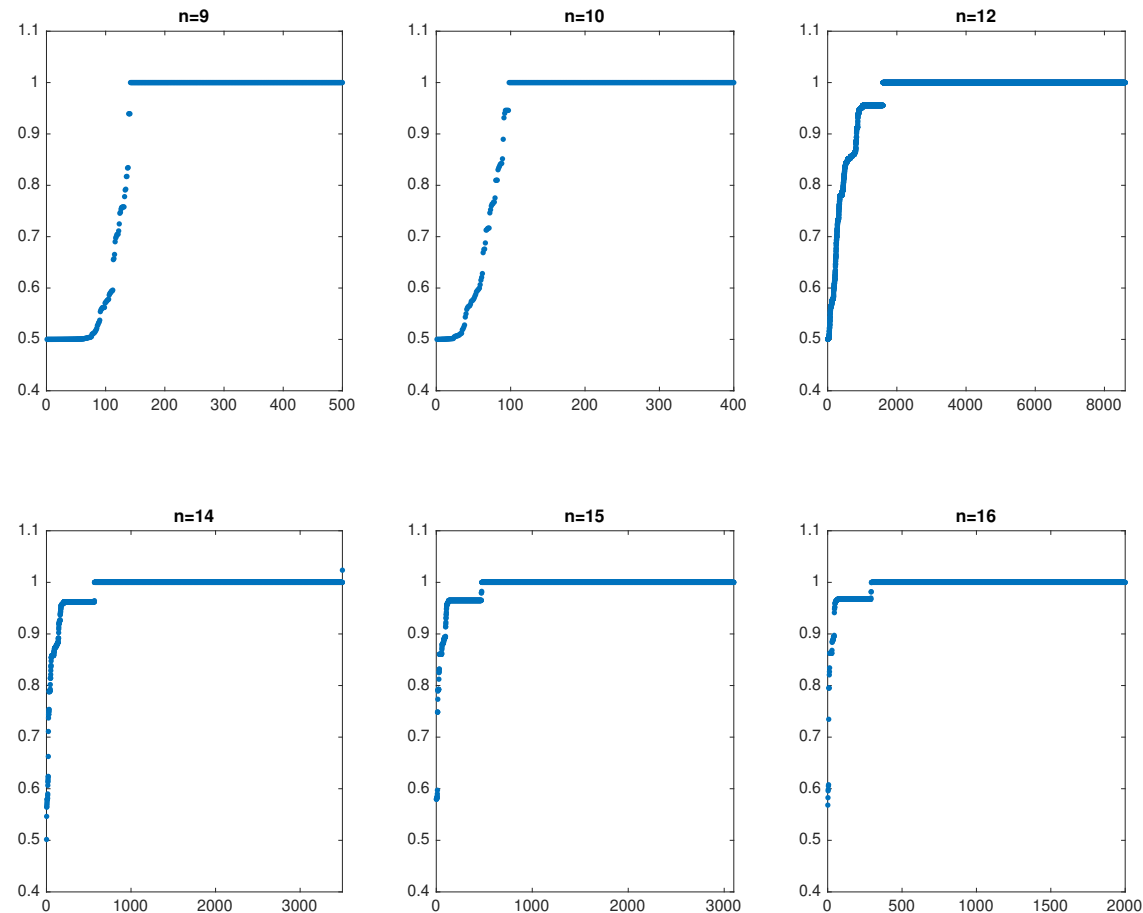
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Sorted final values of the Crouzeix ratio f
found starting from **many** randomly generated initial points.



Results for Larger Dimension n and Degree $n - 1$

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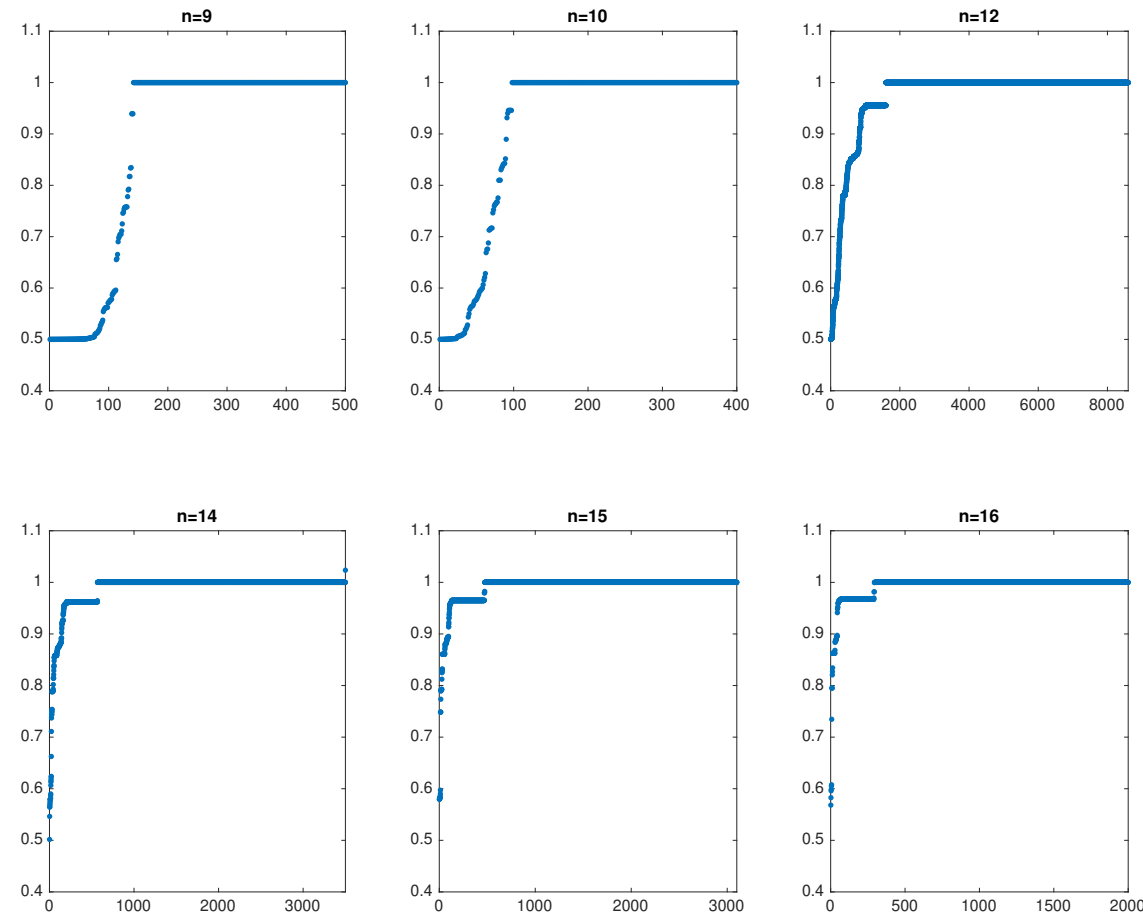
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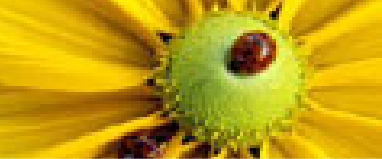
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Sorted final values of the Crouzeix ratio f
found starting from **many** randomly generated initial points.
There **are** other locally optimal values of f between 0.5 and 1 !



An Apparent Local Minimum: $N = 14$

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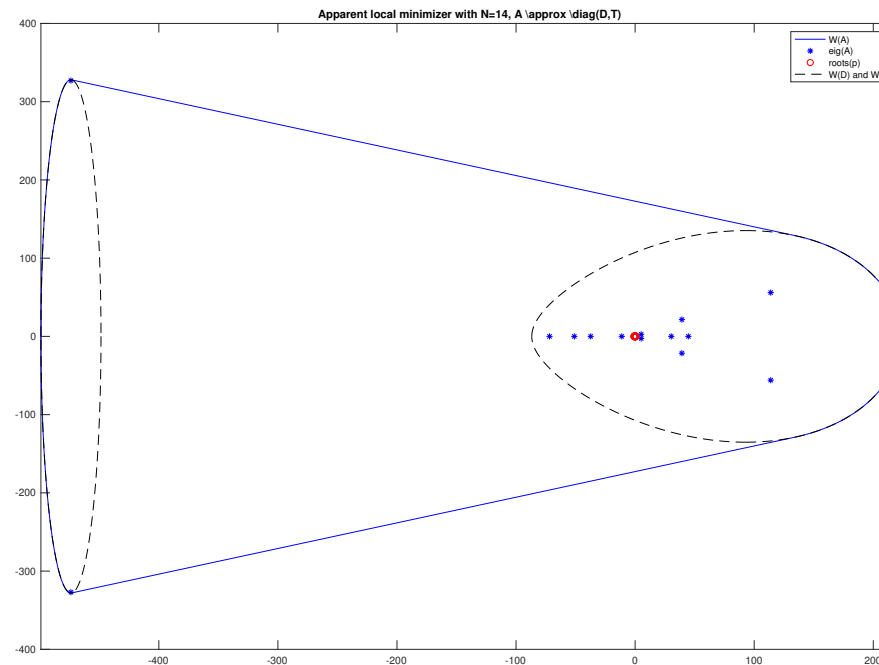
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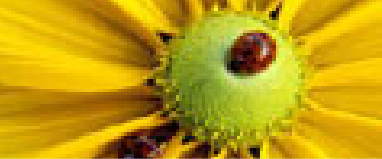
The apparently locally optimal matrix A is nearly unitarily similar to a block diagonal matrix with a 2×2 block A_{11} and a 14×14 block A_{22} .

Black dashed curves show boundaries of field of values of final computed A_{11} and A_{22}

Solid blue curve is boundary of field of values of final computed A

Blue asterisks are eigenvalues of final computed A

Small red circles are roots of final computed p



What if we Fix p and Optimize over A ?

Experiments fixing p with degree m and optimizing over A with order $\geq m + 1$ led us to:

Theorem 1. For any fixed polynomial p of degree $m \geq 1$, there exists a divergent sequence $\{A^{(k)}\}$ of order $n = m + 1$ for which $f(p, A^{(k)}) \rightarrow 0.5$ as $k \rightarrow \infty$. Furthermore, we can choose $A^{(k)}$ so $\{W(A^{(k)})\}$ is a sequence of disks with radius $\rightarrow \infty$.

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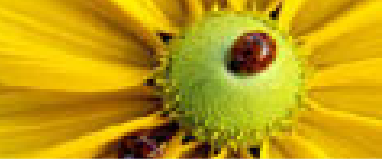
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However, 0.5 is not attained.

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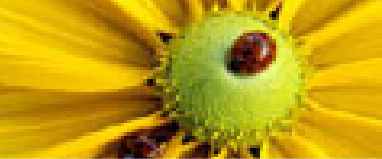
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However, 0.5 is not attained.

Experiments fixing p with degree m and optimizing over A with order $\leq m$ led us to:

Theorem 2. Fix p to have degree m with at least two distinct roots. Then, for all n with $2 \leq n \leq m$, there exists a convergent sequence of $n \times n$ matrices $\{A^{(k)}\}$ for which the Crouzeix ratio $f(p, A^{(k)}) \rightarrow 0.5$. Furthermore, we can choose $A^{(k)}$ so $\{W(A^{(k)})\}$ is a sequence of disks shrinking to a root of p .

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What if we Fix p and Optimize over A ?

Experiments fixing p with degree m and optimizing over A with order $\geq m + 1$ led us to:

Theorem 1. For any fixed polynomial p of degree $m \geq 1$, there exists a divergent sequence $\{A^{(k)}\}$ of order $n = m + 1$ for which $f(p, A^{(k)}) \rightarrow 0.5$ as $k \rightarrow \infty$. Furthermore, we can choose $A^{(k)}$ so $\{W(A^{(k)})\}$ is a sequence of disks with radius $\rightarrow \infty$.

However, 0.5 is not attained.

Experiments fixing p with degree m and optimizing over A with order $\leq m$ led us to:

Theorem 2. Fix p to have degree m with at least two distinct roots. Then, for all n with $2 \leq n \leq m$, there exists a convergent sequence of $n \times n$ matrices $\{A^{(k)}\}$ for which the Crouzeix ratio $f(p, A^{(k)}) \rightarrow 0.5$. Furthermore, we can choose $A^{(k)}$ so $\{W(A^{(k)})\}$ is a sequence of disks shrinking to a root of p .

However, 0.5 is not attained.

Crouzeix's Conjecture

Nonsmooth
Optimization of
the Crouzeix Ratio f

Nonsmoothness of
the Crouzeix Ratio
BFGS

Experiments
Optimizing over A
(order n) and p (deg
 $\leq n - 1$)

Final Fields of Values
for Lowest Computed
 f

Optimizing over both
 p and A : Final
 $f(p, A)$

Is the Ratio 0.5
Attained?

How Could we
Recognize such
Minimizers?

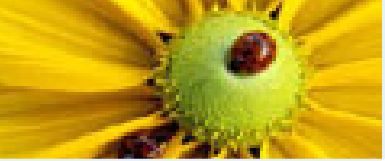
Final Fields of Values
for f Closest to 1

Why is the Crouzeix
Ratio One?

Results for Larger
Dimension n and
Degree $n - 1$

An Apparent Local
Minimum: $N = 14$

What if we Fix p and
Optimize over A ?



Crouzeix's Conjecture

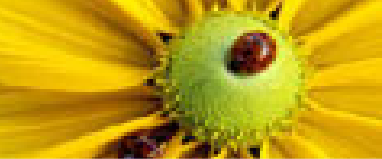
Nonsmooth
Optimization of
the Crouzeix Ratio f

Nonsmooth Analysis of the Crouzeix Ratio

The Clarke
Subdifferential
The Gradient or
Subgradients of the
Crouzeix Ratio
Regularity
Simplest Case where
Crouzeix Ratio is
Nonsmooth
 (\hat{c}, \hat{A}) is a
Nonsmooth
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 $f(\cdot, \cdot)$
The General Case
 (\hat{c}, \hat{A}) is a
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Is the Crouzeix Ratio
Globally Clarke
Regular?

Concluding Remarks

Nonsmooth Analysis of the Crouzeix Ratio



The Clarke Subdifferential

Crouzeix's Conjecture

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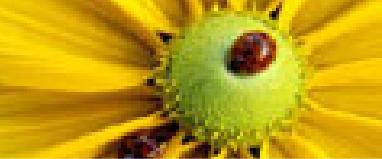
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Concluding Remarks

Assume $h : \mathbb{R}^n \rightarrow \mathbb{R}$ is locally Lipschitz, and
let $D = \{x \in \mathbb{R}^n : h \text{ is differentiable at } x\}$.



The Clarke Subdifferential

Crouzeix's Conjecture

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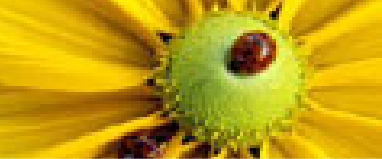
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Assume $h : \mathbb{R}^n \rightarrow \mathbb{R}$ is locally Lipschitz, and
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Rademacher's Theorem: $\mathbb{R}^n \setminus D$ has measure zero.



The Clarke Subdifferential

Crouzeix's Conjecture

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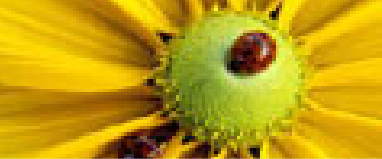
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The Clarke subdifferential, or set of subgradients, of h at \bar{x} is

$$\partial h(\bar{x}) = \text{conv} \left\{ \lim_{x \rightarrow \bar{x}, x \in D} \nabla h(x) \right\}.$$



The Clarke Subdifferential

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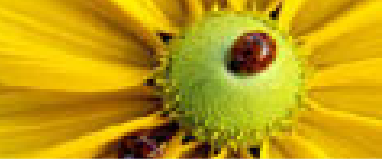
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Crouzeix's Conjecture

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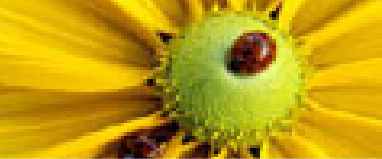
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If h is continuously differentiable at \bar{x} , then $\partial h(\bar{x}) = \{\nabla h(\bar{x})\}$.



The Clarke Subdifferential

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Nonsmooth
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Nonsmooth Analysis
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The Gradient or
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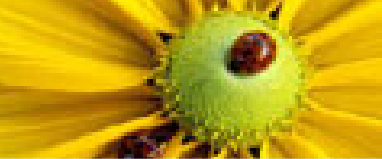
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We say \bar{x} is *Clarke stationary* for h if $0 \in \partial h(\bar{x})$ (a *nonsmooth* stationary point if $0 \in \partial h(\bar{x})$ contains more than one vector)



The Clarke Subdifferential

Crouzeix's Conjecture

Nonsmooth Optimization of the Crouzeix Ratio f

Nonsmooth Analysis of the Crouzeix Ratio

The Clarke Subdifferential

The Gradient or Subgradients of the Crouzeix Ratio

Regularity

Simplest Case where Crouzeix Ratio is

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Stationary Point of $f(\cdot, \cdot)$

The General Case

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Is the Crouzeix Ratio Globally Clarke Regular?

Concluding Remarks

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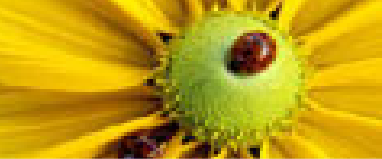
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Clarke stationarity is a *necessary condition* for local or global optimality.



The Gradient or Subgradients of the Crouzeix Ratio

For the numerator, we need the variational properties of

$$\max_{\theta \in [0, 2\pi]} |p(z_\theta)| \quad \text{where} \quad z_\theta = v_\theta^* A v_\theta.$$

Crouzeix's Conjecture

Nonsmooth
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Nonsmooth Analysis
of the Crouzeix Ratio

The Clarke
Subdifferential

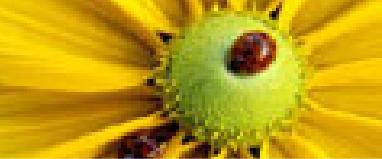
The Gradient or
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Regularity
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- the gradient of $p(z_\theta)$ w.r.t. the coefficients of p

Crouzeix's Conjecture

Nonsmooth
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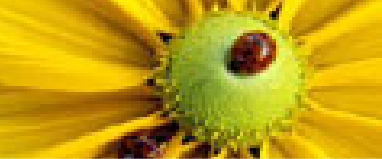
Regularity
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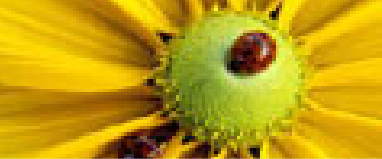
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Crouzeix's Conjecture

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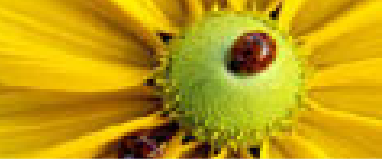
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If the max of $|p(z_\theta)|$ is attained by a unique point $\hat{\theta}$, then all these are evaluated at $\hat{\theta}$ and combined with the gradient of $|\cdot|$ to obtain the gradient of the numerator.

Crouzeix's Conjecture

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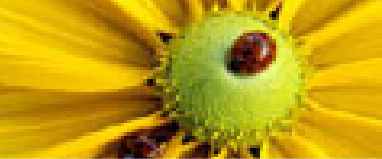
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Otherwise, need to take the *convex hull* of these gradients over all maximizing θ to get the subgradients of the numerator.

Crouzeix's Conjecture

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For the denominator, combine:

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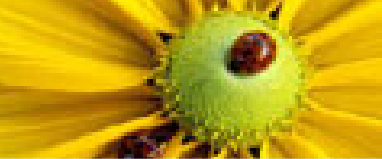
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Otherwise, need to take the *convex hull* of these gradients over all maximizing θ to get the subgradients of the numerator.

For the denominator, combine:

- the gradient or subgradients of the 2-norm (maximum singular value) of a matrix (involves the singular vectors)

Crouzeix's Conjecture

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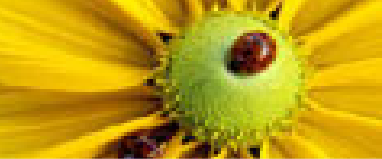
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- the gradient of $p(z_\theta)$ w.r.t. the coefficients of p
- the gradient of $p(z_\theta)$ w.r.t. z_θ
- the gradient of $z_\theta(A) = v_\theta^* A v_\theta$ w.r.t. A

If the max of $|p(z_\theta)|$ is attained by a unique point $\hat{\theta}$, then all these are evaluated at $\hat{\theta}$ and combined with the gradient of $|\cdot|$ to obtain the gradient of the numerator.

Otherwise, need to take the *convex hull* of these gradients over all maximizing θ to get the subgradients of the numerator.

For the denominator, combine:

- the gradient or subgradients of the 2-norm (maximum singular value) of a matrix (involves the singular vectors)
- the gradient of the matrix polynomial $p(A)$ w.r.t. A (involves differentiating A^k w.r.t. A , resulting in Kronecker products).

Crouzeix's Conjecture

Nonsmooth
Optimization of
the Crouzeix Ratio f

Nonsmooth Analysis
of the Crouzeix Ratio

The Clarke
Subdifferential

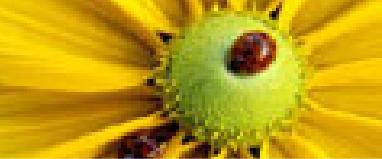
The Gradient or
Subgradients of the
Crouzeix Ratio

Regularity
Simplest Case where
Crouzeix Ratio is
Nonsmooth
 (\hat{c}, \hat{A}) is a
Nonsmooth
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 $f(\cdot, \cdot)$

The General Case
 (\hat{c}, \hat{A}) is a
Nonsmooth
Stationary Point of
 $f(\cdot, \cdot)$

Is the Crouzeix Ratio
Globally Clarke
Regular?

Concluding Remarks



The Gradient or Subgradients of the Crouzeix Ratio

For the numerator, we need the variational properties of

$$\max_{\theta \in [0, 2\pi]} |p(z_\theta)| \quad \text{where} \quad z_\theta = v_\theta^* A v_\theta.$$

- the gradient of $p(z_\theta)$ w.r.t. the coefficients of p
- the gradient of $p(z_\theta)$ w.r.t. z_θ
- the gradient of $z_\theta(A) = v_\theta^* A v_\theta$ w.r.t. A

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For the denominator, combine:

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- the gradient of the matrix polynomial $p(A)$ w.r.t. A (involves differentiating A^k w.r.t. A , resulting in Kronecker products).

Finally, use the quotient rule.

Crouzeix's Conjecture

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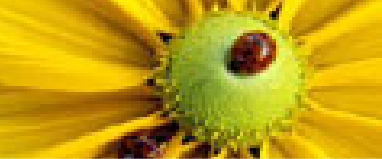
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The Gradient or
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Regularity

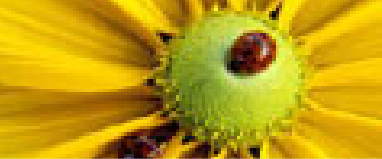
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Is the Crouzeix Ratio
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Concluding Remarks

A directionally differentiable, locally Lipschitz function h is *regular* (in the sense of Clarke, 1975) near a point x when its directional derivative $x \mapsto h'(x; d)$ is upper semicontinuous there for every fixed direction d .



Regularity

Crouzeix's Conjecture

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Nonsmooth Analysis
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The Clarke
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The Gradient or
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Regularity

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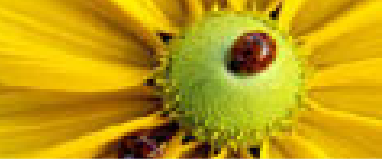
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In this case $0 \in \partial h(x)$ is equivalent to the first-order optimality condition $h'(x, d) \geq 0$ for all directions d .



Regularity

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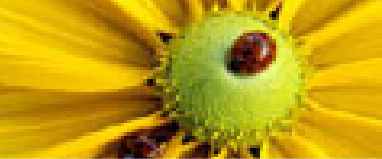
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- All convex functions are regular



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- All convex functions are regular
- All continuously differentiable functions are regular



Regularity

Crouzeix's Conjecture

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Nonsmooth Analysis
of the Crouzeix Ratio

The Clarke
Subdifferential
The Gradient or
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Regularity

Simplest Case where
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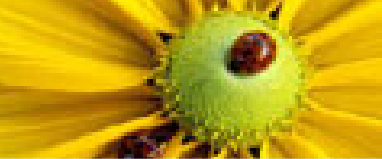
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In this case $0 \in \partial h(x)$ is equivalent to the first-order optimality condition $h'(x, d) \geq 0$ for all directions d .

- All convex functions are regular
- All continuously differentiable functions are regular
- Nonsmooth concave functions, e.g. $h(x) = -|x|$, are not regular.



Simplest Case where Crouzeix Ratio is Nonsmooth

Crouzeix's Conjecture

Nonsmooth
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Nonsmooth Analysis
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The Gradient or
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Regularity

Simplest Case where
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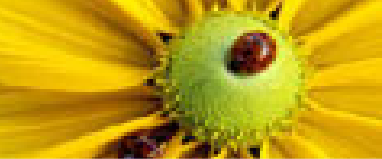
The General Case

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Is the Crouzeix Ratio
Globally Clarke
Regular?

Concluding Remarks

Optimize over complex monic linear polynomials $p(z) \equiv c + z$ and complex matrices with order $n = 2$. Let $f(p, A) \equiv f(c, A)$, where now $f : \mathbb{C} \times \mathbb{C}^{2 \times 2} \rightarrow \mathbb{R}$.



Simplest Case where Crouzeix Ratio is Nonsmooth

Crouzeix's Conjecture

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Regularity

Simplest Case where
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(\hat{c}, \hat{A}) is a
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The General Case

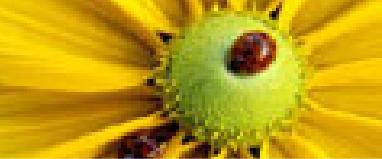
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Let $\hat{c} = 0$ ($\hat{p}(z) = z$) and $\hat{A} = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}$, so $W(\hat{A}) = \overline{\mathcal{D}}$, the unit disk, and hence $|p(z)|$ is maximized everywhere on the unit circle, with f nonsmooth at (\hat{c}, \hat{A}) and $f(\hat{c}, \hat{A}) = 1/2$.



Simplest Case where Crouzeix Ratio is Nonsmooth

Crouzeix's Conjecture

Nonsmooth
Optimization of
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Nonsmooth Analysis
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The Clarke
Subdifferential
The Gradient or
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Crouzeix Ratio

Regularity

Simplest Case where
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(\hat{c}, \hat{A}) is a
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The General Case

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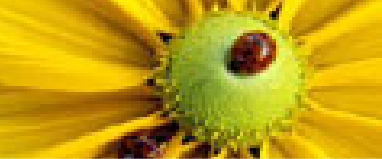
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Theorem 3. The Crouzeix ratio f is regular at (\hat{c}, \hat{A}) , with

$$\partial f(\hat{c}, \hat{A}) = \text{conv}_{\theta \in [0, 2\pi)} \left\{ \left(\frac{1}{2} e^{-i\theta}, \frac{1}{4} \begin{bmatrix} e^{-i\theta} & 0 \\ e^{-2i\theta} & e^{-i\theta} \end{bmatrix} \right) \right\}$$



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

Nonsmooth
Optimization of
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Nonsmooth Analysis
of the Crouzeix Ratio

The Clarke
Subdifferential
The Gradient or
Subgradients of the
Crouzeix Ratio

Regularity
Simplest Case where
Crouzeix Ratio is
Nonsmooth

(\hat{c}, \hat{A}) is a
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 $f(\cdot, \cdot)$

The General Case

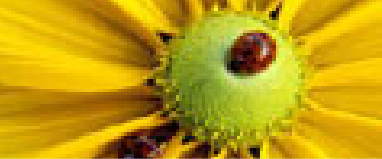
(\hat{c}, \hat{A}) is a
Nonsmooth
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Is the Crouzeix Ratio
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Concluding Remarks

Corollary.

$$0 \in \partial f(\hat{c}, \hat{A})$$



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

Nonsmooth
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The Clarke
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Regularity
Simplest Case where
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The General Case

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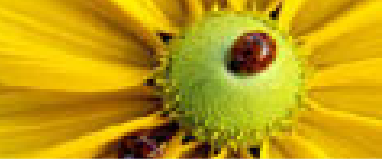
Is the Crouzeix Ratio
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Concluding Remarks

Corollary.

$$0 \in \partial f(\hat{c}, \hat{A})$$

Proof: the vectors inside the convex hull defined by $\theta = 0, 2\pi/3$ and $4\pi/3$ sum to zero.



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

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The Clarke
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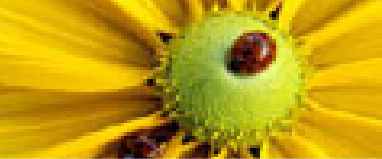
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$$0 \in \partial f(\hat{c}, \hat{A})$$

Proof: the vectors inside the convex hull defined by $\theta = 0, 2\pi/3$ and $4\pi/3$ sum to zero.

Actually, we knew this must be true as Crouzeix's conjecture is known to hold for $n = 2$, and hence (\hat{c}, \hat{A}) is a global minimizer of $f(\cdot, \cdot)$, but we can extend the result to larger values of m, n , for which we don't know whether the conjecture holds.



The General Case

Optimize over complex polynomials $p(z) \equiv c_0 + \cdots + c_m z^m$ and complex matrices with order n . Let $f(p, A) \equiv f(c, A)$, where $f : \mathbb{C}^{m+1} \times \mathbb{C}^{n \times n} \rightarrow \mathbb{R}$.

Crouzeix's Conjecture

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Regularity
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Optimize over complex polynomials $p(z) \equiv c_0 + \cdots + c_m z^m$ and complex matrices with order n . Let $f(p, A) \equiv f(c, A)$, where $f : \mathbb{C}^{m+1} \times \mathbb{C}^{n \times n} \rightarrow \mathbb{R}$.

Let $\hat{c} = [0, 0, \dots, 1]$, corresponding to the polynomial z^m , and \hat{A} equal the C -matrix of order $n = m + 1$ so $W(\hat{A}) = \overline{\mathcal{D}}$, the closed unit disk, and hence $f(\hat{c}, \hat{A}) = 1/2$.

Crouzeix's Conjecture

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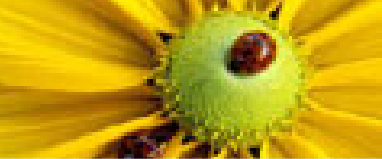
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Theorem 4. The Crouzeix ratio on $(c, A) \in \mathbb{C}^{m+1} \times \mathbb{C}^{n \times n}$ is regular at (\hat{c}, \hat{A}) with

$$\partial f(\hat{c}, \hat{A}) = \text{conv}_{\theta \in [0, 2\pi)} \left\{ (y_\theta, Y_\theta) \right\}$$

where

$$y_\theta = \frac{1}{2} [z^m, z^{m-1}, \dots, z, 0]^T$$

and Y_θ is the $n \times n$ matrix

$$Y_\theta = \frac{1}{4} \begin{bmatrix} z & 0 & \sqrt{2}z^{-1} & \sqrt{2}z^{-2} & \cdots & \sqrt{2}z^{3-n} & z^{2-n} \\ \sqrt{2}z^2 & 2z & 0 & 2z^{-1} & \cdots & 2z^{4-n} & \sqrt{2}z^{3-n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \sqrt{2}z^{n-2} & 2z^{n-3} & 2z^{n-4} & 2z^{n-5} & \cdots & 0 & \sqrt{2}z \\ \sqrt{2}z^{n-1} & 2z^{n-2} & 2z^{n-3} & 2z^{n-4} & \cdots & 2z & 0 \\ z^n & \sqrt{2}z^{n-1} & \sqrt{2}z^{n-2} & \sqrt{2}z^{n-3} & \cdots & \sqrt{2}z^2 & z \end{bmatrix}$$

with $z = e^{-i\theta}$.

Crouzeix's Conjecture

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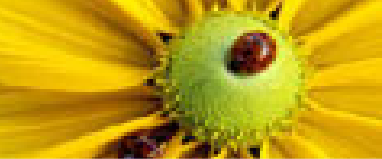
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Is the Crouzeix Ratio
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Concluding Remarks



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

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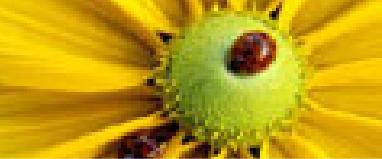
Is the Crouzeix Ratio
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Concluding Remarks

Corollary.

$$0 \in \partial f(\hat{c}, \hat{A})$$

so, for any n , the pair (\hat{c}, \hat{A}) is a nonsmooth stationary point of f .



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

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Corollary.

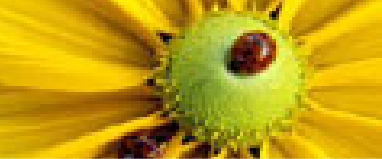
$$0 \in \partial f(\hat{c}, \hat{A})$$

so, for any n , the pair (\hat{c}, \hat{A}) is a nonsmooth stationary point of f .

Proof. The convex combination

$$\frac{1}{n+1} \sum_{k=0}^n (y_{2k\pi/(n+1)}, Y_{2k\pi/(n+1)})$$

is zero.



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

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Crouzeix Ratio

Regularity
Simplest Case where
Crouzeix Ratio is
Nonsmooth

(\hat{c}, \hat{A}) is a
Nonsmooth
Stationary Point of
 $f(\cdot, \cdot)$

The General Case

(\hat{c}, \hat{A}) is a
Nonsmooth
Stationary Point of
 $f(\cdot, \cdot)$

Is the Crouzeix Ratio
Globally Clarke
Regular?

Concluding Remarks

Corollary.

$$0 \in \partial f(\hat{c}, \hat{A})$$

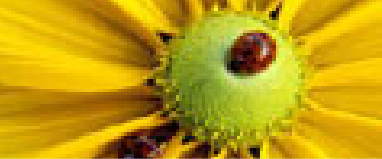
so, for any n , the pair (\hat{c}, \hat{A}) is a nonsmooth stationary point of f .

Proof. The convex combination

$$\frac{1}{n+1} \sum_{k=0}^n (y_{2k\pi/(n+1)}, Y_{2k\pi/(n+1)})$$

is zero.

This is a necessary condition for (\hat{c}, \hat{A}) to be a local (or global) minimizer of f on $\mathbb{R}^{m+1} \times \mathbb{R}^{n \times n}$. This is a new result for $n > 2$.



(\hat{c}, \hat{A}) is a Nonsmooth Stationary Point of $f(\cdot, \cdot)$

Crouzeix's Conjecture

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the Crouzeix Ratio f

Nonsmooth Analysis
of the Crouzeix Ratio

The Clarke
Subdifferential
The Gradient or
Subgradients of the
Crouzeix Ratio

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This is a necessary condition for (\hat{c}, \hat{A}) to be a local (or global) minimizer of f on $\mathbb{R}^{m+1} \times \mathbb{R}^{n \times n}$. This is a new result for $n > 2$. And by regularity, it implies that the directional derivative $f'(\cdot, d) \geq 0$ for all directions d .



Is the Crouzeix Ratio Globally Clarke Regular?

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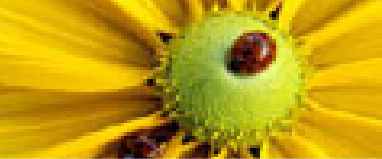
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Is the Crouzeix Ratio Globally Clarke Regular?

No. Let $\tilde{p}(\zeta) = \zeta$ and

$$\tilde{A}(t) = \begin{bmatrix} 0 & \sqrt{2} & 2t \\ 0 & 0 & \sqrt{2} \\ 0 & 0 & 0 \end{bmatrix}$$

for which $W(A(0))$ is a disk and $f(\tilde{p}, \tilde{A}(0)) = 1/\sqrt{2}$.
The Crouzeix ratio f is not regular at $(\tilde{p}, \tilde{A}(0))$.

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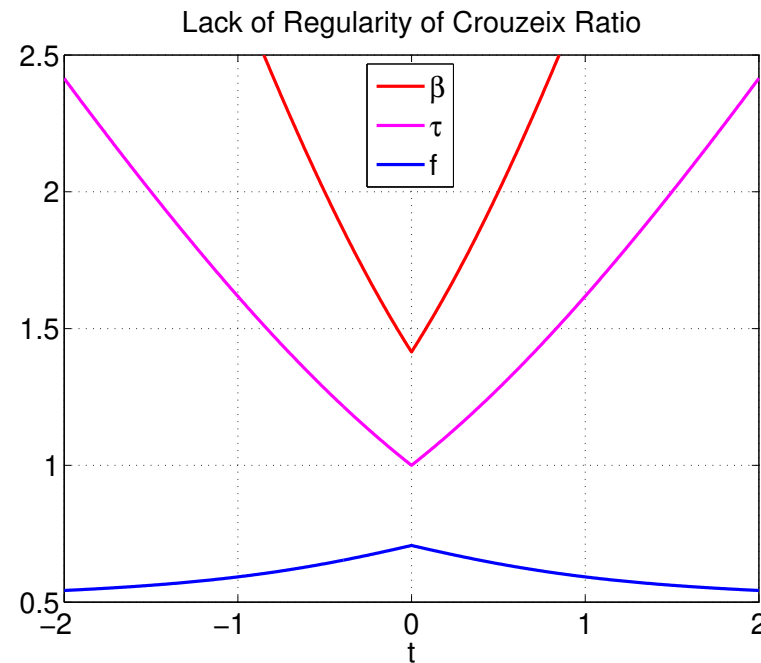


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Plot of the denominator β , the numerator τ and the Crouzeix ratio f evaluated at $(\tilde{p}, \tilde{A}(t))$, $t \in [-2, 2]$.

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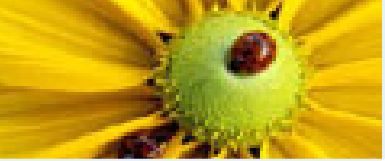
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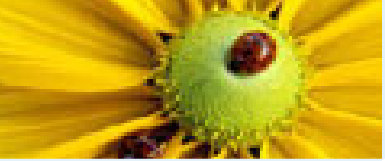
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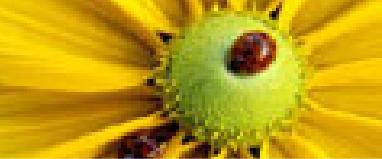
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Summary

Both Chebfun and BFGS perform remarkably reliably despite nonsmoothness that can occur either in the boundary of the field of values (w.r.t. the complex plane) or in the Crouzeix ratio function (w.r.t the polynomial-matrix space).

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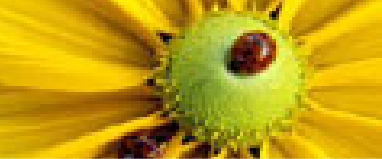
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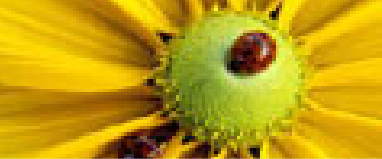
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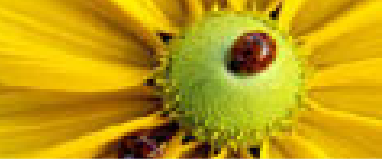
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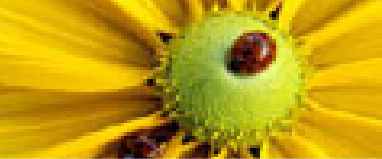
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The results strongly support Crouzeix's conjecture: the globally minimal value of the Crouzeix ratio $f(p, A)$ is 0.5.



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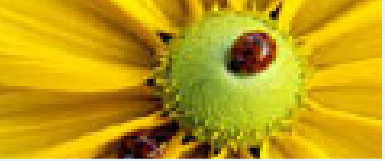
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A. Greenbaum and M.L. Overton
Numerical Investigation of Crouzeix's Conjecture
Linear Alg. Appl., 2017

A. Greenbaum, A.S. Lewis and M.L. Overton
Variational Analysis of the Crouzeix Ratio
Math. Programming, 2016

M.L. Overton
*Local Minimizers of the Crouzeix Ratio: A Nonsmooth Optimization
Case Study*
Calcolo, 2022

All available at www.cs.nyu.edu/overton



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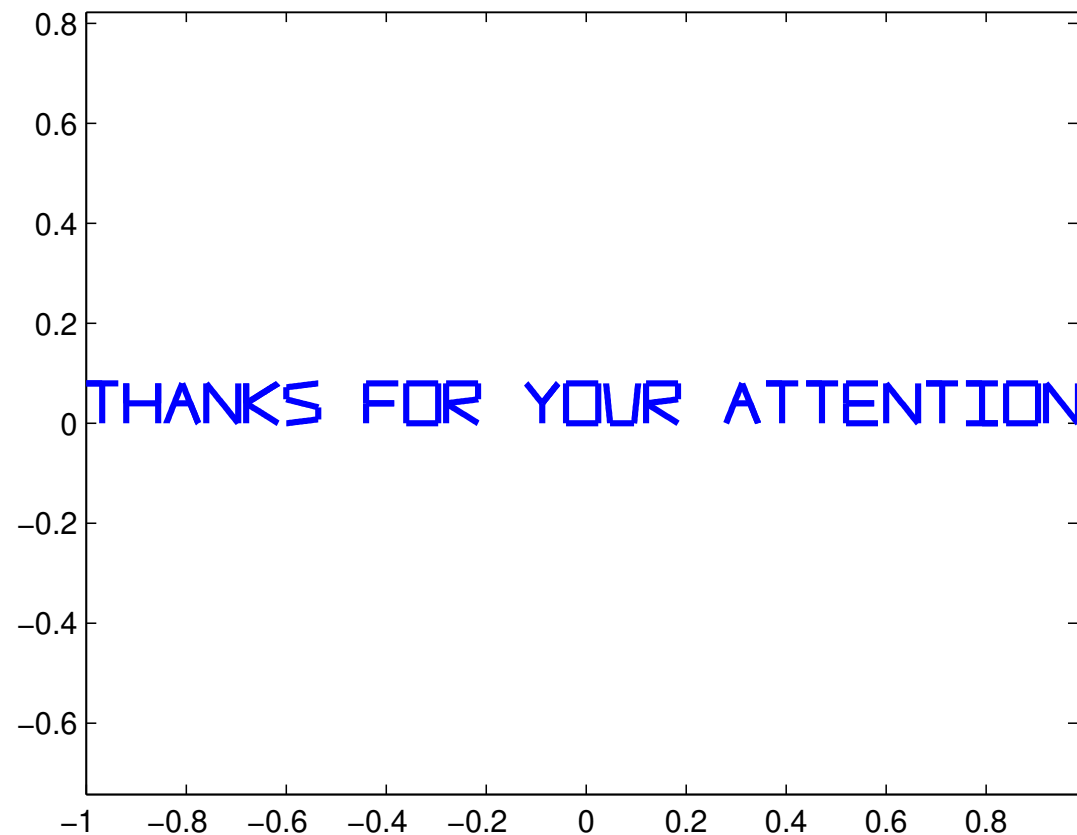
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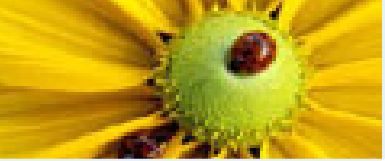
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```
% define and plot a chebfun with 87 pieces  
%s=scribble('Thanks for your attention');  
%plot(s,'b','LineWidth',2), axis equal
```





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```
plot(exp(3i*s), 'm', 'LineWidth', 2), axis equal
```

